

Simultaneous Localization and Mapping (SLAM) for Indoor Navigation



Video

Fig.: First SLAM test by Harley Lara.



The system consists of:

- PX4 flight controller
- NVIDIA Jetson Xavier NX
- Intel Tracking Cam
- Intel Depth Cam
- Hexacopter frame flamewheel

From:

<https://student-wiki.eolab.de/> - HSRW EOLab Students Wiki

Permanent link:

<https://student-wiki.eolab.de/doku.php?id=drones:slam:start&rev=1645801283>

Last update: **2023/01/05 14:38**

