

Trough Automation PCB - Documentation

Here you can find all the necessary information to work with the Trough Automation PCB in your own project.

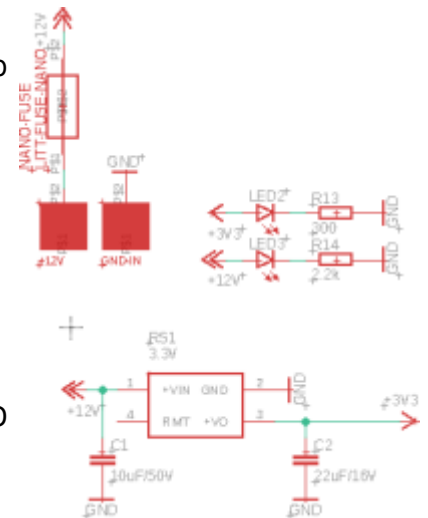
General Concept and internal workings

The board was developed as an easy tool to switch high loads remotely and automatically based on sensor readings done by the same board or even other sensors in the surroundings. It can connect to Wifi and can also be reconfigured without programming the whole board, thanks to [Tasmota](#).

The board's main chip is an ESP8266, more specifically the [ESP-12F](#). It can control a relay and has a current meter connected to the ADC which meters the current attached to the high voltage output. Furthermore, all GPIOs are available for attaching sensors. GPIO 14 is routed out specifically for OneWire Devices.

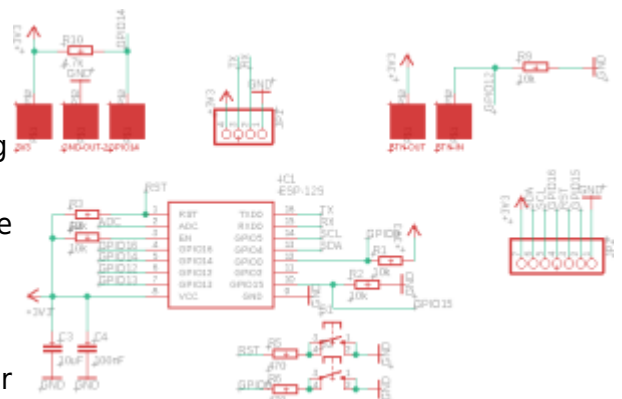
Power Management

The power management side is held pretty simple. The main work is done by a [daughter board by RS Pro](#). It has an input voltage of 4.75V to 36V and can deliver a maximum of 500mA. It puts out a constant voltage of 3.3V, used by all the controlling electronics. The remote pin of the module is not used or routed out at the moment. This could be used as an on and off switch. In front of the regulator sits a nano fuse. This can differ from board to board. (So have a close look at that!) There are status LEDs for both 12V and 3.3V. When using another voltage than 12V, R14 may have to be adjusted, so the LED does not blow out. Both should light up clearly when using the board with 12V. When only 3.3V is connected to the programming header, the 3.3V LED will light up normally but the 12V LED will not be fully lit up. Never connect an FTDI-Breakout to the 3.3V-Pin when a high voltage is connected to the board!



MCU

The ESP8266/ESP-12F is implemented as described in the datasheet: [Datasheet ESP12-F \(5. Application circuit\)](#). Furthermore, some extra parts got added. To program the board it has to be set into the programming mode. Therefore two extra buttons are needed. These are hooked up to the reset pin and GPIO0. Two GPIOs are routed to specific solder pads needed in the application as a trough-automation. GPIO14 is pulled high so OneWire sensors like the DS18B20 can be attached directly to the solder pads. There are also solder pads for



From:
<https://student-wiki.eolab.de/> - **HSRW EOLab Students Wiki**

Permanent link:
https://student-wiki.eolab.de/doku.php?id=eolab:ioa_trough_automation:documentation:start&rev=1646652596

Last update: **2023/01/05 14:38**

